



$$x_0 - a_{x0} \cdot t_0^2 + b_{x0} \cdot t_0 + c_{x0} = e_{x0} \quad (2-6)$$

- c. Repeat steps (b) and (c) for all of the  $n$  observations and accumulate the errors into  $e_x$

$$e_x = \sum_{i=0}^{n-1} |x_i - a_{xi} \cdot t_i^2 + b_{xi} \cdot t_i + c_{xi}| \quad (2-7)$$

Where  $|X|$  is the absolute value of  $X$ .

The optimization algorithm tries to improve its *guesses* of the parameters (a, b, and c) over the iterations to find the *optimum* values in the search space that *minimizes* the error  $e_x$ .

Fig. 2-10 visualizes a 2D search space (two parameters), where the horizontal axes represent the domains of the two parameters and the vertical axis represents the value of the objective function (the error). The optimization algorithm should start from any point on the search space and move iteratively towards the minimum error (i.e. the global optimum).

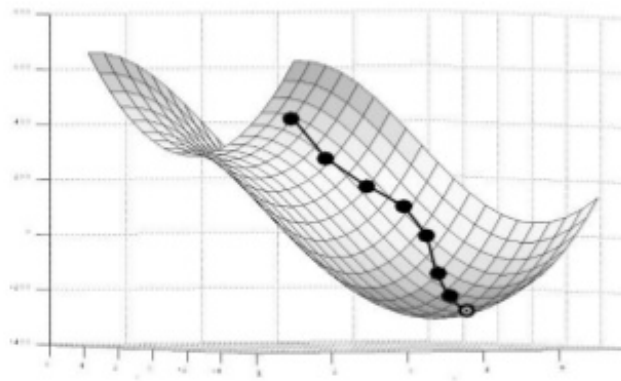


Fig. 2-10 Minimization example in a 2D search space

Searching the search space for the optimum (minimum or maximum) solution depends on the optimization algorithm. The next section explains evolution-strategy optimization algorithms.

After optimizing a function, it is saved for usage as a model for an observed phenomenon or an environmental object. For example, the goalkeeper robot can keep the optimized functions (1), (2), and (3) for similar future shoots (Assuming that all shoots have similar paths).

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